

Reading: Jackson 5.1 through 5.12, 5.15 through 5.18

Review of basic magnetostatics (i.e., cases with steady currents):

There are no magnetic monopoles.

Magnetic-flux density (or, magnetic induction) \vec{B} is produced by currents.

Continuity eqn: $\frac{\partial \rho}{\partial t} + \nabla \cdot \vec{J} = 0$

In magnetostatics, $\nabla \cdot \vec{J} = 0$

\vec{J} is current density: amount of positive charge crossing unit area per unit time

Biot-Savart Law: A current I flowing along a differential length element $d\vec{l}$ yields a differential flux density $d\vec{B}$ at position \vec{x} (points from length element to observation point):

$$d\vec{B} = \frac{\mu_0}{4\pi} I \frac{d\vec{l} \times \vec{x}}{|\vec{x}|^3}$$

$$I d\vec{l} = J da d\vec{l} = \vec{J} d^3x$$

Force on an element of current: $d\vec{F} = I d\vec{l} \times \vec{B} = \vec{J} \times \vec{B} d^3x$

Torque on a magnetic dipole: $\vec{N} = \vec{\mu} \times \vec{B}$

For a distribution of current with density $\vec{J}(\vec{x})$ exposed to an external \vec{B} ,

$$\vec{F} = \int d\vec{F} = \int \vec{J} \times \vec{B} d^3x \qquad \vec{N} = \int \vec{x} \times (\vec{J} \times \vec{B}) d^3x$$

Biot-Savart: $d\vec{B} = \frac{\mu_0}{4\pi} \frac{\vec{J} \times (\vec{x} - \vec{x}')}{|\vec{x} - \vec{x}'|^3} d^3x'$ (field at \vec{x} due to current at \vec{x}')

$$\Rightarrow \vec{B}(\vec{x}) = \frac{\mu_0}{4\pi} \int \vec{J}(\vec{x}') \times \frac{\vec{x} - \vec{x}'}{|\vec{x} - \vec{x}'|^3} d^3x'$$

Since $\frac{\vec{x} - \vec{x}'}{|\vec{x} - \vec{x}'|^3} = -\nabla_x \left(\frac{1}{|\vec{x} - \vec{x}'|} \right)$,

$$\vec{B}(\vec{x}) = -\frac{\mu_0}{4\pi} \int \vec{J}(\vec{x}') \times \nabla_x \left(\frac{1}{|\vec{x} - \vec{x}'|} \right) d^3x'$$

$$\vec{B}(\vec{x}) = -\frac{\mu_0}{4\pi} \int \vec{J}(\vec{x}') \times \nabla_x \left(\frac{1}{|\vec{x} - \vec{x}'|} \right) d^3x'$$

Vector identity: $\nabla \times (\psi \vec{a}) = \nabla\psi \times \vec{a} + \psi \nabla \times \vec{a}$

$$\Rightarrow \vec{a} \times \nabla\psi = \psi \nabla \times \vec{a} - \nabla \times (\psi \vec{a})$$

$$\Rightarrow \vec{J}(\vec{x}') \times \nabla_x \left(\frac{1}{|\vec{x} - \vec{x}'|} \right) = \frac{1}{|\vec{x} - \vec{x}'|} \nabla_x \times \vec{J}(\vec{x}') - \nabla_x \times \left[\frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} \right]$$



= 0 since $\vec{J}(\vec{x}')$ doesn't depend on \vec{x}

$$\Rightarrow \vec{B}(\vec{x}) = \frac{\mu_0}{4\pi} \int \nabla_x \times \left[\frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} \right] d^3x' = \frac{\mu_0}{4\pi} \nabla_x \times \int \frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} d^3x'$$

Since $\nabla \cdot (\nabla \times \vec{a}) = 0$, $\nabla \cdot \vec{B} = 0$

$$\nabla \times \vec{B} = \frac{\mu_0}{4\pi} \nabla \times \left[\nabla \times \int \frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} d^3x' \right]$$

$$\nabla \times (\nabla \times \vec{a}) = \nabla(\nabla \cdot \vec{a}) - \nabla^2 \vec{a}$$

$$\begin{aligned} \nabla_x \times \vec{B}(\vec{x}) &= \frac{\mu_0}{4\pi} \left[\nabla_x \left(\nabla_x \cdot \int \frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} d^3 x' \right) - \nabla_x^2 \int \frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} d^3 x' \right] \\ &= \frac{\mu_0}{4\pi} \nabla_x \int \nabla_x \cdot \left[\frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} \right] d^3 x' - \frac{\mu_0}{4\pi} \int \nabla_x^2 \left[\frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} \right] d^3 x' \end{aligned}$$

Vector identity: $\nabla \cdot (\psi \vec{a}) = \vec{a} \cdot \nabla \psi + \psi \nabla \cdot \vec{a}$

$$\Rightarrow \nabla_x \cdot \left[\frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} \right] = \vec{J}(\vec{x}') \cdot \nabla_x \left(\frac{1}{|\vec{x} - \vec{x}'|} \right) + \frac{1}{|\vec{x} - \vec{x}'|} \nabla_x \cdot \vec{J}(\vec{x}') \quad \uparrow = 0 \text{ since } \vec{J}(\vec{x}') \text{ doesn't depend on } \vec{x}$$

Also, $\nabla_x^2 \left[\frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} \right] = \vec{J}(\vec{x}') \nabla_x^2 \left(\frac{1}{|\vec{x} - \vec{x}'|} \right) \Rightarrow$

$$\nabla_x \times \vec{B}(\vec{x}) = \frac{\mu_0}{4\pi} \nabla_x \int \vec{J}(\vec{x}') \cdot \nabla_x \left(\frac{1}{|\vec{x} - \vec{x}'|} \right) d^3 x' - \frac{\mu_0}{4\pi} \int \vec{J}(\vec{x}') \nabla_x^2 \left(\frac{1}{|\vec{x} - \vec{x}'|} \right) d^3 x'$$

$$\nabla_x \times \vec{B}(\vec{x}) = \frac{\mu_0}{4\pi} \nabla_x \int \vec{J}(\vec{x}') \cdot \nabla_x \left(\frac{1}{|\vec{x} - \vec{x}'|} \right) d^3x' - \frac{\mu_0}{4\pi} \int \vec{J}(\vec{x}') \nabla_x^2 \left(\frac{1}{|\vec{x} - \vec{x}'|} \right) d^3x'$$

$$\nabla_x \left(\frac{1}{|\vec{x} - \vec{x}'|} \right) = -\nabla_{x'} \left(\frac{1}{|\vec{x} - \vec{x}'|} \right) \quad \text{and} \quad \nabla_x^2 \left(\frac{1}{|\vec{x} - \vec{x}'|} \right) = -4\pi \delta(\vec{x} - \vec{x}')$$

$$\begin{aligned} \Rightarrow \nabla_x \times \vec{B}(\vec{x}) &= -\frac{\mu_0}{4\pi} \nabla_x \int \vec{J}(\vec{x}') \cdot \nabla_{x'} \left(\frac{1}{|\vec{x} - \vec{x}'|} \right) d^3x' + \mu_0 \int \vec{J}(\vec{x}') \delta(\vec{x} - \vec{x}') d^3x' \\ &= -\frac{\mu_0}{4\pi} \nabla_x \int \left\{ \nabla_{x'} \cdot \left[\frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} \right] - \frac{\nabla_{x'} \cdot \vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} \right\} d^3x' + \mu_0 \vec{J}(\vec{x}) \end{aligned}$$

$\nabla \cdot \vec{J} = 0$ in magnetostatics

$$\Rightarrow \nabla_x \times \vec{B}(\vec{x}) = -\frac{\mu_0}{4\pi} \nabla_x \int \frac{\vec{J}(\vec{x}') \cdot d\vec{a}'}{|\vec{x} - \vec{x}'|} + \mu_0 \vec{J}(\vec{x}) \quad \Rightarrow \quad \nabla \times \vec{B} = \mu_0 \vec{J}$$



= 0 for a localized current dist

Consider an open surface S bounded by a closed curve C .

$$\int_S (\nabla \times \vec{B}) \cdot d\vec{a} = \mu_0 \int_S \vec{J} \cdot d\vec{a}$$

Stokes's Thm $\Rightarrow \oint_C \vec{B} \cdot d\vec{l} = \mu_0 I$ (Ampère's Law)

The Vector Potential (Jackson sec 5.4)

We want to solve the eqns of magnetostatics:

$$\nabla \cdot \vec{B} = 0 \quad \nabla \times \vec{B} = \mu_0 \vec{J}$$

If $\vec{J} = 0$ in the region of interest, then we can introduce a **magnetic scalar potential** Φ_M and $\vec{B} = -\nabla\Phi_M$. In this case, we can use the techniques of electrostatics for solving Laplace's eqn (more later).

More generally, $\nabla \cdot \vec{B} = 0 \Rightarrow \vec{B}(\vec{x}) = \nabla \times \vec{A}(\vec{x})$

$\vec{A}(\vec{x})$ is the “**vector potential**”.

From Jackson 5.16 (or, p 3 of lecture notes),

$$\vec{A}(\vec{x}) = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} d^3x' + \nabla\Psi(\vec{x}) \quad [2^{\text{nd}} \text{ term is OK since } \nabla \times (\nabla\Psi) = 0.]$$

$\vec{A} \rightarrow \vec{A} + \nabla\Psi$ is called a “gauge transformation”.

We can use gauge transformations to yield a convenient form for $\nabla \cdot \vec{A}$.

$$\nabla \times (\nabla \times \vec{A}) = \mu_0 \vec{J} \quad \Rightarrow \quad \nabla(\nabla \cdot \vec{A}) - \nabla^2 \vec{A} = \mu_0 \vec{J}$$

Coulomb gauge: $\nabla \cdot \vec{A} = 0$

$\Rightarrow \nabla^2 \vec{A} = -\mu_0 \vec{J}$ (each Cartesian component of \vec{A} satisfies Poisson's eqn)

$$\begin{aligned} \nabla_x \cdot \vec{A}(\vec{x}) &= \nabla_x \cdot \left[\frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} d^3x' + \nabla_x \Psi(\vec{x}) \right] \\ &= \frac{\mu_0}{4\pi} \int \nabla_x \cdot \left[\frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} \right] d^3x' + \nabla_x^2 \Psi(\vec{x}) \end{aligned}$$

$$\int \nabla_x \cdot \left[\frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} \right] d^3 x' = 0 \quad \text{for all space if the current dist}$$

is localized (from slides 4 and 5)

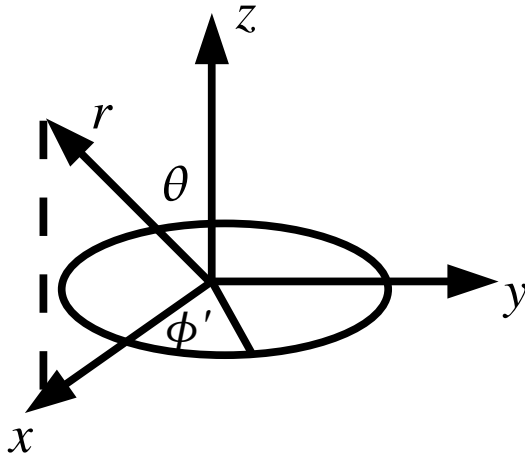
$$\text{So, } \nabla \cdot \vec{A} = 0 \quad \Rightarrow \quad \nabla^2 \Psi = 0$$

$\Rightarrow \Psi = \text{const}$ for Coulomb gauge applied to all space

$$\Rightarrow \vec{A}(\vec{x}) = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} d^3 x'$$

Analogous to scalar potential for all space: $\Phi(\vec{x}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{x}')}{|\vec{x} - \vec{x}'|} d^3 x'$

A Circular Current Loop (Jackson sec 5.5)



The loop has radius a , lies in the x - y plane, is centered on the origin, and carries current I .

Spherical coords: \vec{J} is in the $\hat{\phi}$ direction.

$$\vec{A}(\vec{x}) = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} d^3x'$$

$$\vec{J}(\vec{x}') d^3x' = I d\vec{l}' = I a d\phi' (-\sin \phi' \hat{x} + \cos \phi' \hat{y})$$

Cylindrical symmetry \Rightarrow freedom to place observation point in the x - z plane ($\phi = 0$)

$$\begin{aligned} |\vec{x} - \vec{x}'|^2 &= (x - x')^2 + (y - y')^2 + (z - z')^2 \\ &= (r \sin \theta - a \cos \phi')^2 + (0 - a \sin \phi')^2 + (r \cos \theta - 0)^2 \\ &= r^2 \sin^2 \theta + a^2 \cos^2 \phi' - 2ar \sin \theta \cos \phi' + a^2 \sin^2 \phi' + r^2 \cos^2 \theta \\ &= r^2 + a^2 - 2ar \sin \theta \cos \phi' \end{aligned}$$

$$\vec{A}(\vec{x}) = \frac{\mu_0 I a}{4\pi} \int_0^{2\pi} \frac{d\phi' (-\sin \phi' \hat{x} + \cos \phi' \hat{y})}{\sqrt{r^2 + a^2 - 2ar \sin \theta \cos \phi'}}$$

The \hat{x} integral vanishes

(substitute $u = r^2 + a^2 - 2ar \sin \theta \cos \phi'$ and the endpoints are the same)

$\Rightarrow \vec{A}(\vec{x})$ is in the \hat{y} direction, which is also the $\hat{\phi}$ direction.

$$\text{So, } A_r = 0, \quad A_\theta = 0, \quad \text{and} \quad A_\phi(r, \theta) = \frac{\mu_0 I a}{4\pi} \int_0^{2\pi} \frac{\cos \phi' d\phi'}{\sqrt{r^2 + a^2 - 2ar \sin \theta \cos \phi'}}$$

If $r \gg a$, then $(r^2 + a^2 - 2ar \sin \theta \cos \phi')^{-1/2} \approx \frac{1}{r} \left(1 + \frac{a}{r} \sin \theta \cos \phi'\right)$

$$\Rightarrow A_\phi = \frac{\mu_0 I a}{4\pi r} \int_0^{2\pi} d\phi' \cos \phi' \left(1 + \frac{a}{r} \sin \theta \cos \phi'\right) = \frac{\mu_0 I a^2 \sin \theta}{4\pi r^2} \pi$$

$$\vec{B} = \nabla \times \vec{A}$$

$$B_r = \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta A_\phi) = \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} \left(\frac{\mu_0 \pi a^2 I}{4\pi r^2} \sin^2 \theta \right) = \frac{\mu_0}{2\pi} (\pi a^2 I) \frac{\cos \theta}{r^3}$$

$$B_\theta = -\frac{1}{r} \frac{\partial}{\partial r} (r A_\phi) = -\frac{1}{r} \frac{\partial}{\partial r} \left(\frac{\mu_0 \pi a^2 I \sin \theta}{4\pi} r^{-1} \right) = \frac{\mu_0}{4\pi} (\pi a^2 I) \frac{\sin \theta}{r^3}$$

$$B_\phi = 0$$

Recall electric dipole fields:

$$E_r = \frac{1}{2\pi\epsilon_0} p \frac{\cos \theta}{r^3} \quad E_\theta = \frac{1}{4\pi\epsilon_0} p \frac{\sin \theta}{r^3} \quad E_\phi = 0$$

=> magnetic field has dipole character,
with magnetic dipole moment $m = \pi a^2 I$

Next, consider the magnetic induction far from a localized, arbitrary current dist (Jackson sec 5.6).

$$\vec{A}(\vec{x}) = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} d^3 x'$$

$$\begin{aligned} \frac{1}{|\vec{x} - \vec{x}'|} &= \left(|\vec{x}|^2 + |\vec{x}'|^2 - 2\vec{x} \cdot \vec{x}' \right)^{-1/2} \\ &= \frac{1}{|\vec{x}|} \left(1 + \frac{|\vec{x}'|^2}{|\vec{x}|^2} - \frac{2\vec{x} \cdot \vec{x}'}{|\vec{x}|^2} \right)^{-1/2} \\ &= \frac{1}{|\vec{x}|} \left(1 + \frac{\vec{x} \cdot \vec{x}'}{|\vec{x}|^2} + \dots \right) \\ &= \frac{1}{|\vec{x}|} + \frac{\vec{x} \cdot \vec{x}'}{|\vec{x}|^3} + \dots \end{aligned}$$

So, each Cartesian component is

$$A_i(\vec{x}) = \frac{\mu_0}{4\pi} \left[\frac{1}{|\vec{x}|} \int J_i(\vec{x}') d^3 x' + \frac{\vec{x}}{|\vec{x}|^3} \cdot \int J_i(\vec{x}') \vec{x}' d^3 x' + \dots \right]$$

To further simplify, we first derive a useful result. Suppose $f(\vec{x}')$ and $g(\vec{x}')$ are arbitrary functions and $\vec{J}(\vec{x}')$ is localized (but not necessarily divergenceless).

$$\int f g \vec{J} \cdot d\vec{a}' = 0 \quad \text{for a localized current dist}$$

$$\Rightarrow \int \nabla_{x'} \cdot (f g \vec{J}) d^3 x' = 0$$

$$\begin{aligned} \nabla_{x'} \cdot (f g \vec{J}) &= \vec{J} \cdot \nabla_{x'}(f g) + f g \nabla_{x'} \cdot \vec{J} \\ &= f \vec{J} \cdot \nabla_{x'} g + g \vec{J} \cdot \nabla_{x'} f + f g \nabla_{x'} \cdot \vec{J} \end{aligned}$$

\Rightarrow

$$\int \left(f \vec{J} \cdot \nabla_{x'} g + g \vec{J} \cdot \nabla_{x'} f + f g \nabla_{x'} \cdot \vec{J} \right) d^3 x' = 0 \quad (1)$$

Now, take $f = 1$, $g = x'_i$, and impose $\nabla_{x'} \cdot \vec{J} = 0$

$$\Rightarrow \int \left(\underbrace{\vec{J} \cdot \nabla_{x'} x'_i}_{=0} + \underbrace{x'_i \vec{J} \cdot \nabla_{x'} (1)}_{=0} + x'_i \nabla_{x'} \cdot \vec{J} \right) d^3 x' = 0$$

$$\nabla_{x'} x'_i = \frac{\partial x'_i}{\partial x'_1} \hat{x}'_1 + \frac{\partial x'_i}{\partial x'_2} \hat{x}'_2 + \frac{\partial x'_i}{\partial x'_3} \hat{x}'_3 = \hat{x}'_i$$

$$\Rightarrow \int \vec{J} \cdot \hat{x}'_i d^3 x' = \int J_i(\vec{x}') d^3 x' = 0$$

$$\Rightarrow A_i(\vec{x}) \approx \frac{\mu_0}{4\pi} \frac{\vec{x}}{|\vec{x}|^3} \cdot \int J_i(\vec{x}') \vec{x}' d^3 x'$$

With $f = x'_i$, $g = x'_j$, and $\nabla_{x'} \cdot \vec{J} = 0$ in (1),

$$\int \left(x'_i \vec{J} \cdot \nabla_{x'} x'_j + x'_j \vec{J} \cdot \nabla_{x'} x'_i \right) d^3 x' = 0$$

$$\Rightarrow \int \left(x'_i J_j + x'_j J_i \right) d^3 x' = 0$$

$$\begin{aligned}
\vec{x} \cdot \int \vec{x}' J_i d^3 x' &= \sum_j x_j \int x'_j J_i d^3 x' \\
&= \sum_j x_j \int \left[x'_j J_i - \frac{1}{2} (x'_i J_j + x'_j J_i) \right] d^3 x' \\
&= -\frac{1}{2} \sum_j x_j \int (x'_i J_j - x'_j J_i) d^3 x'
\end{aligned}$$

$$\begin{aligned}
i = 1 : \quad \sum_j x_j (x'_i J_j - x'_j J_i) \\
&= x_1 (x'_1 J_1 - x'_1 J_1) + x_2 (x'_1 J_2 - x'_2 J_1) + x_3 (x'_1 J_3 - x'_3 J_1) \\
&= [\vec{x} \times (\vec{x}' \times \vec{J})]_1
\end{aligned}$$

Likewise for $i = 2, 3$

$$\Rightarrow \quad \vec{x} \cdot \int J_i(\vec{x}') \vec{x}' d^3 x' = -\frac{1}{2} \left[\vec{x} \times \int \vec{x}' \times \vec{J}(\vec{x}') d^3 x' \right]_i \quad (2)$$

$$\Rightarrow \quad \vec{A}(\vec{x}) = \frac{\mu_0}{4\pi} \left(-\frac{1}{2} \right) \frac{1}{|\vec{x}|^3} \vec{x} \times \int \vec{x}' \times \vec{J}(\vec{x}') d^3 x'$$

Define the magnetic moment density, or magnetization, as

$$\vec{M}(\vec{x}) = \frac{1}{2} \vec{x} \times \vec{J}(\vec{x})$$

magnetic moment $\vec{m} = \int \vec{M}(\vec{x}') d^3x' = \frac{1}{2} \int \vec{x}' \times \vec{J}(\vec{x}') d^3x'$

$$\Rightarrow \vec{A}(\vec{x}) \approx \frac{\mu_0}{4\pi} \frac{(-1)}{|\vec{x}|^3} \vec{x} \times \vec{m} = \frac{\mu_0}{4\pi} \frac{\vec{m} \times \vec{x}}{|\vec{x}|^3}$$

$$\vec{B} = \nabla \times \vec{A} = \frac{\mu_0}{4\pi} \nabla \times \left(\frac{\vec{m} \times \vec{x}}{|\vec{x}|^3} \right)$$

Using lots of identities on the cover of Jackson, and with

\hat{n} = a unit vector along \vec{x} :

$$\begin{aligned} \nabla \times \left(\frac{\vec{m} \times \vec{x}}{|\vec{x}|^3} \right) &= \nabla \left(\frac{1}{|\vec{x}|^3} \right) \times (\vec{m} \times \vec{x}) + \frac{1}{|\vec{x}|^3} \nabla \times (\vec{m} \times \vec{x}) \\ &= -\frac{3}{|\vec{x}|^4} \hat{n} \times (\vec{m} \times \vec{x}) + \frac{1}{|\vec{x}|^3} [\vec{m} \nabla \cdot \vec{x} - \vec{x} \nabla \cdot \vec{m} + (\vec{x} \cdot \nabla) \vec{m} - (\vec{m} \cdot \nabla) \vec{x}] \end{aligned}$$

$$= -\frac{3}{|\vec{x}|^4} \hat{n} \times (\vec{m} \times \vec{x}) + \frac{1}{|\vec{x}|^3} \left[\underset{=3}{\vec{m} \nabla \cdot \vec{x}} - \underset{=0}{\vec{x} \nabla \cdot \vec{m}} + \underset{=0}{(\vec{x} \cdot \nabla) \vec{m}} - (\vec{m} \cdot \nabla) \vec{x} \right]$$

$$= -\frac{3}{|\vec{x}|^4} [(\hat{n} \cdot \vec{x}) \vec{m} - (\hat{n} \cdot \vec{m}) \vec{x}] + \frac{1}{|\vec{x}|^3} [3\vec{m} - \vec{m}]$$

$$= \frac{1}{|\vec{x}|^3} [-3\vec{m} + 3\hat{n} (\hat{n} \cdot \vec{m}) + 3\vec{m} - \vec{m}] = \frac{1}{|\vec{x}|^3} [3\hat{n} (\hat{n} \cdot \vec{m}) - \vec{m}]$$

$$\Rightarrow \vec{B}(\vec{x}) = \frac{\mu_0}{4\pi} \frac{3\hat{n} (\hat{n} \cdot \vec{m}) - \vec{m}}{|\vec{x}|^3}$$

This has the same form as the field due to an electric dipole:

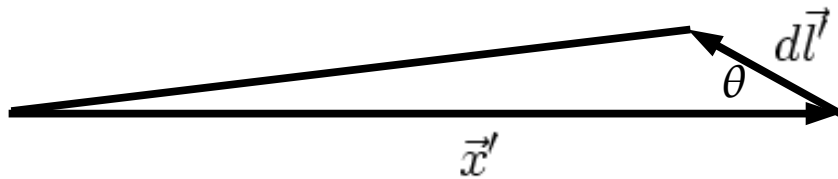
$$\vec{E}(\vec{x}) = \frac{1}{4\pi\epsilon_0} \frac{3\hat{n} (\hat{n} \cdot \vec{p}) - \vec{p}}{|\vec{x}|^3}$$

So, any localized current dist produces a dipole magnetic induction to first order at large distances.

If the current is restricted to a single plane loop (of arbitrary shape),

then $\vec{J}(\vec{x}') d^3x' = I d\vec{l}'$

$$\Rightarrow \vec{m} = \frac{1}{2} \int \vec{x}' \times \vec{J}(\vec{x}') d^3x' = \frac{I}{2} \oint \vec{x}' \times d\vec{l}'$$



$d\vec{l}' \sin \theta =$ height of triangle

$x' =$ base length

$$\frac{1}{2} |\vec{x}' \times d\vec{l}'| = \frac{1}{2} x' d\vec{l}' \sin \theta = \text{area of triangle}$$

$\Rightarrow |\vec{m}| = I \cdot \text{area} ; \vec{m}$ points \perp to the plane (use right hand rule with current)

Note that the circular current loop discussed earlier is a specific case of this general result (see slide 12).

Force and torque on (and energy of) a localized current distribution in an external magnetic induction $\vec{B}(\vec{x})$ (Jackson sec 5.7)

Brief mathematical prelude on the Levi-Civita tensor ϵ_{ijk}

$$\epsilon_{ijk} = 1 \quad \text{for } i, j, k = \begin{matrix} 1, 2, 3 \\ 2, 3, 1 \\ 3, 1, 2 \end{matrix}$$

$$-1 \quad \text{for } i, j, k = \begin{matrix} 1, 3, 2 \\ 2, 1, 3 \\ 3, 2, 1 \end{matrix}$$

0 otherwise (i.e., for 2 or more indices equal)

$$(\vec{a} \times \vec{b})_i = \sum_{jk} \epsilon_{ijk} a_j b_k$$

For example, take $i=1$:

$$\begin{aligned} \sum_{jk} \epsilon_{1jk} a_j b_k &= \epsilon_{123} a_2 b_3 + \epsilon_{132} a_3 b_2 \\ &= a_2 b_3 - a_3 b_2 = (\vec{a} \times \vec{b})_1 \end{aligned}$$

$$\vec{F} = \int \vec{J}(\vec{x}) \times \vec{B}(\vec{x}) d^3x$$

k^{th} component of the induction: $B_k(\vec{x}) = B_k(0) + \vec{x} \cdot \nabla B_k(0) + \dots$

i^{th} component of force:

$$\begin{aligned} F_i &= \int [\vec{J} \times \vec{B}]_i d^3x = \int \sum_{jk} \epsilon_{ijk} J_j(\vec{x}) B_k(\vec{x}) d^3x \\ &= \sum_{jk} \epsilon_{ijk} \int J_j(\vec{x}) [B_k(0) + \vec{x} \cdot \nabla B_k(0) + \dots] d^3x \\ &= \sum_{jk} \epsilon_{ijk} \left[B_k(0) \int J_j(\vec{x}) d^3x + \nabla B_k(0) \cdot \int J_j(\vec{x}) \vec{x} d^3x \right] \\ &\quad \uparrow = 0 \text{ for steady, localized current dist} \\ &\quad \text{(see slide 15)} \end{aligned}$$

Eq (2) on slide 16: $\vec{x} \cdot \int J_i(\vec{x}') \vec{x}' d^3x' = -\frac{1}{2} \left[\vec{x} \times \int \vec{x}' \times \vec{J}(\vec{x}') d^3x' \right]_i$

Replace $\vec{x} \rightarrow \nabla B_k(0)$, $\vec{x}' \rightarrow \vec{x}$, and $i \rightarrow j$

$$\begin{aligned}
\Rightarrow \quad \nabla B_k(0) \cdot \int J_j(\vec{x}) \vec{x} d^3x &= -\frac{1}{2} \left[\nabla B_k(0) \times \int \vec{x} \times \vec{J}(\vec{x}) d^3x \right]_j \\
&= -[\nabla B_k(0) \times \vec{m}]_j \\
&= [\vec{m} \times \nabla B_k(0)]_j
\end{aligned}$$

$$\Rightarrow \quad F_i = \sum_{jk} \epsilon_{ijk} [\vec{m} \times \nabla B_k(0)]_j = \sum_{jk} \epsilon_{ijk} (\vec{m} \times \nabla)_j B_k(\vec{x}) \Big|_{\vec{x}=0}$$

For example, $(\vec{m} \times \nabla)_1 B_k(\vec{x}) \Big|_{\vec{x}=0} = \left(m_2 \frac{\partial}{\partial x_3} - m_3 \frac{\partial}{\partial x_2} \right) B_k(\vec{x}) \Big|_{\vec{x}=0}$

$$\begin{aligned}
&= m_2 \frac{\partial B_k}{\partial x_3}(0) - m_3 \frac{\partial B_k}{\partial x_2}(0) \\
&= [\vec{m} \times \nabla B_k(0)]_1
\end{aligned}$$

$$\Rightarrow \quad \vec{F} = (\vec{m} \times \nabla) \times \vec{B} \Big|_{\vec{x}=0} = \left[\nabla(\vec{m} \cdot \vec{B}) - \vec{m} \nabla \cdot \vec{B} \right]_{\vec{x}=0} \quad \text{(from Jackson cover; explicitly verified on next page)}$$

$$\Rightarrow \quad \vec{F} = \nabla(\vec{m} \cdot \vec{B}) \Big|_{\vec{x}=0}$$

Explicit verification, for $i=1$:

$$\begin{aligned}
 F_1 &= \sum_{jk} \epsilon_{1jk} (\vec{m} \times \nabla)_j B_k \\
 &= (\vec{m} \times \nabla)_2 B_3 - (\vec{m} \times \nabla)_3 B_2 \\
 &= m_3 \frac{\partial B_3}{\partial x_1} - m_1 \frac{\partial B_3}{\partial x_3} - m_1 \frac{\partial B_2}{\partial x_2} + m_2 \frac{\partial B_2}{\partial x_1} \\
 &= m_1 \left(\frac{\partial B_1}{\partial x_1} - \nabla \cdot \vec{B} \right) + m_2 \frac{\partial B_2}{\partial x_1} + m_3 \frac{\partial B_3}{\partial x_1} \\
 &= \frac{\partial}{\partial x_1} (m_1 B_1 + m_2 B_2 + m_3 B_3) - m_1 (\nabla \cdot \vec{B}) \\
 &= \left[\nabla(\vec{m} \cdot \vec{B}) - \vec{m} (\nabla \cdot \vec{B}) \right]_1
 \end{aligned}$$

$$\vec{F} = \nabla(\vec{m} \cdot \vec{B}) \Big|_{\vec{x}=\vec{0}}$$

So, to get the lowest-order force on a current dist due to an external \vec{B} :

- 1) Pick an origin within the dist, 2) Compute \vec{m} wrt that origin,
- 3) Take the derivative $\nabla(\vec{m} \cdot \vec{B})$, 4) Evaluate at the origin.

Torque:
$$\begin{aligned}\vec{N} &= \int \vec{x} \times (\vec{J} \times \vec{B}) d^3x \\ &\approx \int \vec{x} \times [\vec{J} \times \vec{B}(0)] d^3x \\ &= \int [\vec{x} \cdot \vec{B}(0)] \vec{J} d^3x - \vec{B}(0) \int \vec{x} \cdot \vec{J} d^3x\end{aligned}$$

Since $\vec{x} = r\hat{r}$, the second integral is $\int r J_r d^3x$

Recall eq 1 on slide 14:
$$\int (f \vec{J} \cdot \nabla_{x'} g + g \vec{J} \cdot \nabla_{x'} f + fg \nabla_{x'} \cdot \vec{J}) d^3x' = 0$$

Take $f = g = r$, $\nabla \cdot \vec{J} = 0$; $\nabla r = \hat{r}$

$$\Rightarrow \int (r J_r + r J_r) d^3x = 0 \quad \Rightarrow \quad \int \vec{x} \cdot \vec{J} d^3x = 0$$

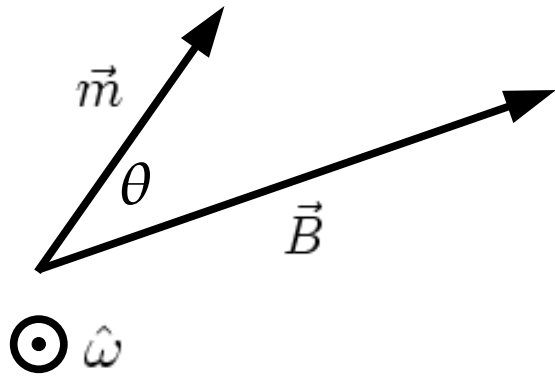
On top of slide 22, we found
$$\int [\vec{x} \cdot \nabla B_k(0)] \vec{J} d^3x = \vec{m} \times \nabla B_k(0)$$

Replace $\nabla B_k(0)$ with $\vec{B}(0) \Rightarrow \int [\vec{x} \cdot \vec{B}(0)] \vec{J} d^3x = \vec{m} \times \vec{B}(0)$

$$\Rightarrow \vec{N} = \vec{m} \times \vec{B}(0) \quad \text{to lowest order}$$

Potential energy of a permanent magnetic dipole in an external induction:

$$\vec{F} = -\nabla U = \nabla(\vec{m} \cdot \vec{B}) \quad \Rightarrow \quad U = -\vec{m} \cdot \vec{B}$$



$$\text{Also, } \vec{N} = -\frac{\partial U}{\partial \theta} \hat{\omega} = \frac{\partial}{\partial \theta}(mB \cos \theta) \hat{\omega} = -mB \sin \theta \hat{\omega} = \vec{m} \times \vec{B}$$

\Rightarrow \vec{m} tends to align along \vec{B} (compass)

Magnetic dipole moment of matter comes from 1) current of electrons and 2) intrinsic magnetic moments of atoms.

As with electrostatics, averaging of the microscopic eqns yields the macroscopic eqns:

$$\nabla \cdot \vec{B} = 0 \quad \nabla \times \vec{H} = \vec{J} \quad (\text{only free current is included here})$$

\vec{H} is called the “magnetic field”.

$$\vec{H} \equiv \frac{1}{\mu_0} \vec{B} - \vec{M} \quad (\vec{M} \text{ is the magnetization, i.e., dipole moment per unit volume})$$

effective current density $\vec{J}_M = \nabla \times \vec{M}$

(Jackson p. 192; analogous to electrostatic development in Topic 4, slides 8 through 10)

For linear, isotropic, paramagnetic and diamagnetic materials,

$$\vec{B} = \mu \vec{H} \quad (\mu \text{ is called the “magnetic permeability”})$$

More complicated for ferromagnetic materials, where \vec{M} depends on history and may be non-zero even for zero applied induction.

Boundary conditions:

$$(\vec{B}_2 - \vec{B}_1) \cdot \hat{n} = 0 \qquad \hat{n} \times (\vec{H}_2 - \vec{H}_1) = \vec{K}$$

\vec{K} = free surface current density (i.e., current per unit transverse length)

First eqn yields $\vec{H}_2 \cdot \hat{n} = \frac{\mu_1}{\mu_2} \vec{H}_1 \cdot \hat{n}$

If $\mu_1 \gg \mu_2$, then \vec{H}_2 has a much larger normal than tangential component (as long as \vec{K} is not huge) $\Rightarrow \vec{H}_2$ is normal to the boundary surface, **just as an external electric field is at a conducting surface.**

$$\nabla \times \vec{H} = 0 \quad \Rightarrow \quad \vec{H} = -\nabla\Phi_M \quad (\text{magnetic scalar potential})$$

$$\begin{aligned} \nabla \cdot \vec{B} = 0 \quad \text{For linear media} \Rightarrow \quad \nabla \cdot (\mu\vec{H}) = 0 \\ \Rightarrow \quad \nabla \cdot (\mu\nabla\Phi_M) = 0 \end{aligned}$$

If μ is piecewise constant, then

$\nabla^2\Phi_M = 0$ in each region of constant μ .

For “hard ferromagnets”, \vec{M} is fixed (doesn't depend on applied field).

$$\nabla \cdot \vec{B} = \nabla \cdot [\mu_0(\vec{H} + \vec{M})] = \mu_0 \nabla \cdot [-\nabla\Phi_M + \vec{M}] = 0$$

$$\Rightarrow \quad \nabla^2\Phi_M = -\rho_M$$

where the effective magnetic-charge density $\rho_M = -\nabla \cdot \vec{M}$

If there are no boundary surfaces, then in analogy with electrostatics

$$\Phi_M(\vec{x}) = -\frac{1}{4\pi} \int \frac{\nabla_{x'} \cdot \vec{M}(\vec{x}')}{|\vec{x} - \vec{x}'|} d^3 x'$$

If \vec{M} is well-behaved and localized, then integration by parts yields

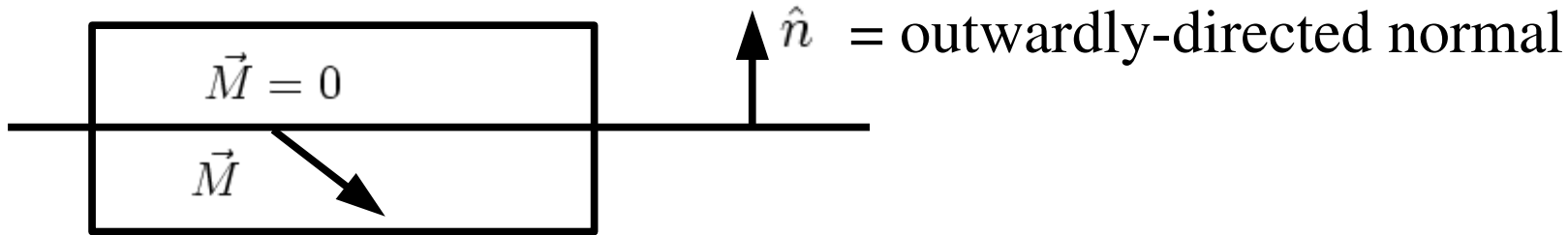
$$\Phi_M(\vec{x}) = -\frac{1}{4\pi} \nabla \cdot \int \frac{\vec{M}(\vec{x}')}{|\vec{x} - \vec{x}'|} d^3 x'$$

Far from the region of non-vanishing magnetization, $\Phi_M(\vec{x}) \approx \frac{\vec{m} \cdot \vec{x}}{4\pi r^3}$

$$\vec{m} = \int \vec{M}(\vec{x}') d^3 x' = \text{magnetic dipole moment}$$

Suppose \vec{M} is discontinuous: $\vec{M} \neq 0$ inside the ferromagnet and $\vec{M} = 0$ outside.

Gaussian pillbox straddling the surface:



“Magnetic charge” inside $q_M = - \int \nabla \cdot \vec{M} d^3x = - \int \vec{M} \cdot d\vec{a} = (-\vec{M}) \cdot (-\hat{n}) A$

\Rightarrow effective magnetic surface-charge density $\sigma_M = \vec{M} \cdot \hat{n}$

$$\Rightarrow \Phi_M(\vec{x}) = -\frac{1}{4\pi} \int_V \frac{\nabla_{x'} \cdot \vec{M}(\vec{x}')}{|\vec{x} - \vec{x}'|} d^3x' + \frac{1}{4\pi} \oint_S \frac{\vec{M}(\vec{x}') \cdot \hat{n}'}{|\vec{x} - \vec{x}'|} da'$$

SP 5.6

If a closed curve C bounds surface S , then
$$\oint_C \vec{E}' \cdot d\vec{l} = -\frac{d}{dt} \int_S \vec{B} \cdot \hat{n} da$$

where \vec{E}' is the electric field at $d\vec{l}$ in its rest frame. The time derivative is a total derivative, accounting both for time variations in \vec{B} and motion of the loop in space.

Adopting the rest frame of the loop:

$$\oint_C \vec{E}' \cdot d\vec{l} = \oint_C \vec{E} \cdot d\vec{l} = \int_S (\nabla \times \vec{E}) \cdot \hat{n} da$$

$$\Rightarrow \int_S \left[(\nabla \times \vec{E}) + \frac{\partial \vec{B}}{\partial t} \right] \cdot \hat{n} da = 0 \quad \Rightarrow \quad \nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

This generalizes $\nabla \times \vec{E} = 0$ for static fields to the dynamic case.

$\oint_C \vec{E} \cdot d\vec{l}$ is called the “electromotive force” (emf)

The work done to generate the currents that yield a static magnetic field is

$$W = \int d^3x \int_0^B \vec{H} \cdot \delta \vec{B}$$

For a linear medium, $W = \frac{1}{2} \int \vec{H} \cdot \vec{B} d^3x$

For a localized current distribution,

$$\begin{aligned} W &= \frac{1}{2} \int \vec{H} \cdot (\nabla \times \vec{A}) d^3x \\ &= \frac{1}{2} \int [\vec{A} \cdot (\nabla \times \vec{H}) - \nabla \cdot (\vec{H} \times \vec{A})] d^3x \\ &= \frac{1}{2} \int \vec{J} \cdot \vec{A} d^3x \end{aligned}$$

Inductance (Jackson sec 5.17)

Consider N current-carrying circuits (the i^{th} one has current I_i) in vacuum.

$$\vec{J}(\vec{x}) = \sum_{i=1}^N \vec{J}_i(\vec{x})$$

$$\begin{aligned} W &= \frac{1}{2} \int \vec{J} \cdot \vec{A} d^3x = \frac{\mu_0}{8\pi} \int d^3x \int d^3x' \frac{\vec{J}(\vec{x}) \cdot \vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} \\ &= \frac{\mu_0}{8\pi} \int d^3x \int d^3x' \left[\sum_{i=1}^N \vec{J}_i(\vec{x}) \right] \cdot \left[\sum_{j=1}^N \vec{J}_j(\vec{x}') \right] \frac{1}{|\vec{x} - \vec{x}'|} \\ &= \frac{\mu_0}{8\pi} \sum_{i=1}^N \int d^3x \sum_{j=1}^N \int d^3x' \frac{\vec{J}_i(\vec{x}) \cdot \vec{J}_j(\vec{x}')}{|\vec{x} - \vec{x}'|} \\ &= \frac{1}{2} \sum_{i=1}^N L_i I_i^2 + \sum_{i=1}^N \sum_{j \neq i}^N M_{ij} I_i I_j \end{aligned}$$

with

$$L_i = \frac{\mu_0}{4\pi I_i^2} \int_{C_i} d^3x \int_{C_i} d^3x' \frac{\vec{J}_i(\vec{x}) \cdot \vec{J}_i(\vec{x}')}{|\vec{x} - \vec{x}'|} \quad (\text{“self-inductance”})$$

$$M_{ij} = \frac{\mu_0}{4\pi I_i I_j} \int_{C_i} d^3x \int_{C_j} d^3x' \frac{\vec{J}_i(\vec{x}) \cdot \vec{J}_j(\vec{x}')}{|\vec{x} - \vec{x}'|} \quad (\text{“mutual inductance”})$$

Note : $M_{ji} = M_{ij}$

If the circuits are negligibly thin, then $\vec{J}_i(\vec{x}) d^3x = I_i d\vec{l}$

$$\Rightarrow M_{ij} = \frac{1}{I_i I_j} \oint_{C_i} I_i d\vec{l} \cdot \vec{A}_j(\vec{x}) = \frac{1}{I_j} \int_S (\nabla \times \vec{A}_j) \cdot \hat{n} da = \frac{1}{I_j} \int_S \vec{B}_j \cdot d\vec{a}$$

= magnetic flux in i due to field produced by j , divided by current in j

Similarly for self-inductance.

$$emf = \oint_C \vec{E} \cdot d\vec{l} = -\frac{d}{dt} \int \vec{B} \cdot d\vec{a} = -\frac{d}{dt}(LI) = -L \frac{dI}{dt} \quad \left(\text{or } -M_{12} \frac{dI_2}{dt} \right)$$

Suppose the variation in \vec{B} is sufficiently slow that \vec{B} dominates over the induced \vec{E}

Conductor: $\vec{J} = \sigma \vec{E}$ ($\sigma = \text{conductivity}$)

Faraday's Law: $\nabla \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0 \Rightarrow \nabla \times \left(\vec{E} + \frac{\partial \vec{A}}{\partial t} \right) = 0$

$$\Rightarrow \vec{E} + \frac{\partial \vec{A}}{\partial t} = -\nabla \Phi \Rightarrow \vec{E} = -\nabla \Phi - \frac{\partial \vec{A}}{\partial t}$$

In cases of negligible free charge, the variation of \vec{B} is the only source of \vec{E}

$$\Rightarrow \vec{E} = -\frac{\partial \vec{A}}{\partial t}$$

Consider a medium with uniform and frequency-independent permeability μ and frequency-independent conductivity σ .

Ampère's Law: $\nabla \times \vec{B} = \mu\vec{J} = \mu\sigma\vec{E}$

$$\Rightarrow \nabla \times (\nabla \times \vec{A}) = -\mu\sigma \frac{\partial \vec{A}}{\partial t}$$

Adopt Coulomb gauge: $\nabla \cdot \vec{A} = 0$

$$\Rightarrow \nabla \times (\nabla \times \vec{A}) = \nabla(\nabla \cdot \vec{A}) - \nabla^2 \vec{A} = -\mu\sigma \frac{\partial \vec{A}}{\partial t}$$

$$\nabla^2 \vec{A} = \mu\sigma \frac{\partial \vec{A}}{\partial t} \quad (\text{diffusion eqn})$$

Taking time derivative:

$$\nabla^2 \left(\frac{\partial \vec{A}}{\partial t} \right) = \mu\sigma \frac{\partial^2 \vec{A}}{\partial t^2} \Rightarrow \nabla^2 \vec{E} = \mu\sigma \frac{\partial \vec{E}}{\partial t} \quad (\text{diffusion eqn again})$$

Suppose the field initially varies on a spatial scale $\sim L$

$$\Rightarrow |\nabla^2 \vec{A}| \sim \frac{A}{L^2}$$

If the timescale for field decay is τ , then $\left| \frac{\partial \vec{A}}{\partial t} \right| \sim \frac{A}{\tau}$

$$\Rightarrow \frac{A}{L^2} \sim \mu\sigma \frac{A}{\tau} \quad \Rightarrow \quad \tau \sim \mu\sigma L^2$$

Or, if the conductor is subjected to external fields that vary with frequency $\nu = \tau^{-1}$, then the fields penetrate into the conductor to a distance

$$L \sim (\mu\sigma\nu)^{-1/2}$$